

$$m\ddot{x}_1 = -k_1 x_1 - k_2 (x_1 - x_2)$$

$$m\ddot{x}_2 = -k_1 x_2 - k_2 (x_2 - x_1)$$

$$\Rightarrow \begin{cases} m\ddot{x}_1 = -(k_1 + k_2)x_1 + k_2 x_2 \\ m\ddot{x}_2 = k_2 x_1 - (k_1 + k_2)x_2 \end{cases}$$

$$\Rightarrow \underbrace{\begin{pmatrix} m & 0 \\ 0 & m \end{pmatrix}}_{\vec{M}} \underbrace{\begin{pmatrix} \ddot{x}_1 \\ \ddot{x}_2 \end{pmatrix}}_{\vec{X}} = - \underbrace{\begin{pmatrix} k_1 + k_2 & -k_2 \\ -k_2 & k_1 + k_2 \end{pmatrix}}_{\vec{K}} \underbrace{\begin{pmatrix} x_1 \\ x_2 \end{pmatrix}}_{\vec{X}}$$

$$\vec{M} \ddot{\vec{X}} = -\vec{K} \vec{X}$$

$$\Rightarrow \ddot{\vec{X}} = -\vec{M}^{-1} \vec{K} \vec{X}$$

$$\text{But } \ddot{\vec{X}} = -\omega^2 \vec{1} \vec{X}$$

$$\Rightarrow \vec{M}^{-1} \vec{K} \vec{X} = \omega^2 \vec{1} \vec{X}$$

$$\therefore (\vec{M}^{-1} \vec{K} - \omega^2 \vec{1}) \vec{X} = 0$$

$$\therefore \det(\vec{M}^{-1} \vec{K} - \omega^2 \vec{1}) = 0.$$

for non-trivial \vec{X} .

$$\vec{M} = \begin{pmatrix} m & 0 \\ 0 & m \end{pmatrix} \Rightarrow \vec{M}^{-1} = \begin{pmatrix} \frac{1}{m} & 0 \\ 0 & \frac{1}{m} \end{pmatrix}$$

$$\vec{K} = \begin{pmatrix} k_1 + k_2 & -k_2 \\ -k_2 & k_1 + k_2 \end{pmatrix}$$

$$\Rightarrow \vec{M}^{-1} \vec{K} = \begin{pmatrix} \frac{1}{m} & 0 \\ 0 & \frac{1}{m} \end{pmatrix} \begin{pmatrix} k_1 + k_2 & -k_2 \\ -k_2 & k_1 + k_2 \end{pmatrix}$$

$$= \begin{pmatrix} \frac{k_1 + k_2}{m} & -\frac{k_2}{m} \\ -\frac{k_2}{m} & \frac{k_1 + k_2}{m} \end{pmatrix}$$

$$\Rightarrow \begin{vmatrix} \frac{k_1 + k_2}{m} - \omega^2 & -\frac{k_2}{m} \\ -\frac{k_2}{m} & \frac{k_1 + k_2}{m} - \omega^2 \end{vmatrix} = 0.$$

$$\Rightarrow \left(\frac{k_1 + k_2}{m} - \omega^2 \right)^2 - \left(\frac{k_2}{m} \right)^2 = 0.$$

$$\Rightarrow (\omega^2)^2 - 2 \left(\frac{k_1 + k_2}{m} \right) \omega^2 + \frac{(k_1 + k_2)^2 - k_2^2}{m^2} = 0.$$

$$\Rightarrow \omega^2 = \frac{\frac{2(k_1 + k_2)}{m} \pm \sqrt{\frac{4(k_1^2 + k_2^2 + 2k_1k_2)}{m^2} - \frac{4k_1(k_1 + 2k_2)}{m^2}}}{2}$$

$$= \frac{k_1 + k_2}{m} \pm \frac{1}{m} \sqrt{k_1^2 + k_2^2 + 2k_1k_2 - k_1^2 - 2k_1k_2}$$

$$= \frac{k_1 + k_2}{m} \pm \frac{k_2}{m}$$

$$= \begin{cases} \frac{k_1 + 2k_2}{m} \\ \frac{k_1}{m} \end{cases}$$

Case I: $\omega_1^2 = \frac{k_1 + 2k_2}{m}$

Let $\vec{X} = \begin{pmatrix} a_1 \\ a_2 \end{pmatrix}$

$$\Rightarrow \begin{pmatrix} \frac{k_1 + k_2}{m} & -\frac{k_2}{m} \\ -\frac{k_2}{m} & \frac{k_1 + k_2}{m} \end{pmatrix} \begin{pmatrix} a_1 \\ a_2 \end{pmatrix} = \frac{k_1 + 2k_2}{m} \begin{pmatrix} a_1 \\ a_2 \end{pmatrix}$$

$$\Rightarrow (k_1 + k_2)a_1 - k_2 a_2 = (k_1 + 2k_2)a_1$$

$$(k_1 + k_2)a_2 - k_2 a_1 = (k_1 + 2k_2)a_2$$

$$\Rightarrow a_2 = -a_1 = -a \quad (\text{say}).$$

\Rightarrow Normalized

$$\vec{X}_1 = \frac{1}{\sqrt{2}a} \begin{pmatrix} a \\ -a \end{pmatrix} = \frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ -1 \end{pmatrix}$$

Identify $\omega_1 = \omega_b = \sqrt{\frac{k_1 + 2k_2}{m}}$

& $|e_b\rangle = \vec{X}_1 = \frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ -1 \end{pmatrix}$
(breathing mode)

Case - II $\omega_2 = \frac{k_1}{m}$; Let $\vec{X}_2 = \begin{pmatrix} b_1 \\ b_2 \end{pmatrix}$.

$$\Rightarrow \begin{pmatrix} \frac{k_1 + k_2}{m} & -\frac{k_2}{m} \\ -\frac{k_2}{m} & \frac{k_1 + k_2}{m} \end{pmatrix} \begin{pmatrix} b_1 \\ b_2 \end{pmatrix} = \frac{k_1}{m} \begin{pmatrix} b_1 \\ b_2 \end{pmatrix}$$

$$\Rightarrow (k_1 + k_2)b_1 - k_2 b_2 = k_1 b_1$$

$$-k_2 b_1 + (k_1 + k_2)b_2 = k_1 b_2$$

$$\Rightarrow b_1 = b_2 = b \text{ (say).}$$

$$\therefore \vec{X}_2 = \frac{1}{\sqrt{2}} b \begin{pmatrix} b \\ b \end{pmatrix} = \frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ 1 \end{pmatrix}$$

Identify $\omega_2 = \omega_p = \sqrt{\frac{k_1}{m}}$ (pendulum mode)

and $|e_p\rangle = \vec{X}_2 = \frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ 1 \end{pmatrix}$.

$$\Rightarrow \langle e_b | = \frac{1}{\sqrt{2}} (1 \quad -1), \quad \langle e_p | = \frac{1}{\sqrt{2}} (1 \quad 1).$$

$$\therefore |e_p\rangle\langle e_p| + |e_b\rangle\langle e_b|$$

$$= \frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ 1 \end{pmatrix} \frac{1}{\sqrt{2}} (1 \ 1) + \frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ -1 \end{pmatrix} \frac{1}{\sqrt{2}} (1 \ -1)$$

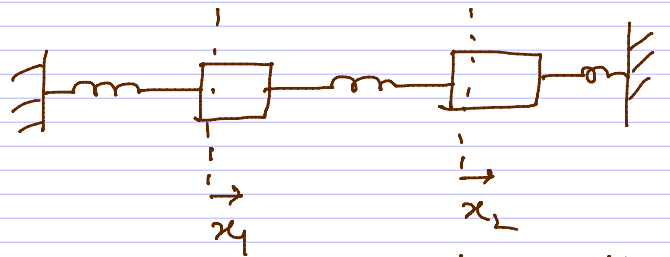
$$= \frac{1}{2} \begin{pmatrix} 1 & 1 \\ 1 & 1 \end{pmatrix} + \frac{1}{2} \begin{pmatrix} 1 & -1 \\ -1 & 1 \end{pmatrix}$$

$$= \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$$

$$= \underbrace{\uparrow\uparrow}_2$$

(Illustrates the idea of complete set of states).

Pendulum mode



Breathing mode

