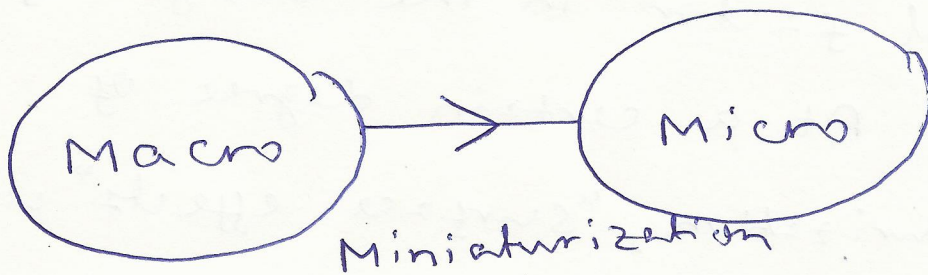


Q: What is more important - Surface tension or Gravity?

PH515 (ADT) ①

Scaling



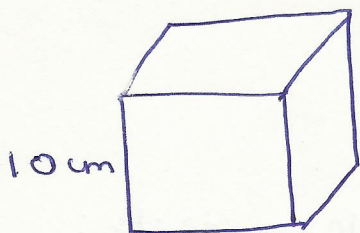
Implications of size reduction

Bread crumb & rubbed plastic rod

Why crumb^{is} attracted but not the entire bread loaf?

Ans. Mass smaller + "MORE".

"MORE": Electrostatic force \propto charge on surface.



$$V = 1000 [\text{cm}^3]$$

$$S = 600 [\text{cm}^2]$$

$$\frac{V}{S} = 1.6 [\text{cm}]$$



$$V = 10^{-3} [\text{cm}^3]$$

$$S = 6 \times 10^{-2} [\text{cm}^2]$$

$$\frac{V}{S} = 0.016 [\text{cm}]$$

As size decreases, volume goes down faster than surface; inertia goes down faster than electrostatic force.

Statement*: Decrease in $\frac{V}{S}$ ratio is a crucial factor in the design of MEMS. At a certain degree of miniaturization, "surface effects" will start dominating over the "Volume effects".

Examples

As $\frac{V}{S}$ decreases,

- "Friction" becomes larger than "Inertia".
- "Heat dissipation" \uparrow ; "Heat storage" \downarrow .
- "Energy coupling" is preferred over "Energy storage".

Demo: Microrobot

Possible projects:

- Tuning fork based "microbee"
- "Microtrimet" [solar powered].
- Android app for magnetic microbot.

[Note: Mr. S. Chowrey received INAE 2014 award for best student project]

* Further details: W. Trimmer, Sensors &

Actuators. 19 267 (1989).

[Title: Microrobot & micromechanical systems].

Variation of physical quantities
as a power of arbitrary scale variable "l".

$$V \sim l^3, \quad S \sim l^2$$

$$\frac{V}{S} \sim l^1.$$

Force	Scaling law
Electrostatic	l^2
Magnetic	l^3
Pressure	l^2
Gravitational	l^4
Surface tension	l^1
Muscle	l^2

{ HW1 (for Electrostatic, Magnetic, Pressure, Gravitational)
 } In class (for Pressure, Gravitational)
 { HW1 (for Surface tension, Muscle)

- Surface tension is annoying for non-fluidic applications.
- Electrostatic force is more interesting than magnetic force as relevant scale goes down.
- more. (HW2: Draw few more possibilities?)

Manufacturing accuracy:

PH515 (ADT)

(4)

A result from solid mechanics for stiffness of a cantilever beam:

$$k = \frac{Y}{4} \frac{w^3 t}{l^3}$$

$l \rightarrow$ length

$w \rightarrow$ width

$t \rightarrow$ thickness

$Y \rightarrow$ Young's modulus.

HW3: How would you decide the tolerance on k (design!).

Brief introduction* to

Hall effect sensing

\leftrightarrow Electronic Compass

&

Piezo sensing

\leftrightarrow Accelerometer

* A (not so) short introduction to MEMS
Frank Chollet, Haobing Liu